



VERIFICATION AND SIMULATION OF NEW DESIGNED NAND FLASH MEMORY CONTROLLER

¹Dr. John Paul Pulipati, Principal, ²Rajesh Durgam, ³M.Shiva Kumar, ⁴P.Venkatapathi, ⁵P.Anitha

¹ Assistant principal@mrce. in, Malla Reddy College of Engineering

² Professor, Dept. of ECE, Malla Reddy College of Engineering

³ Assistant Professor, Dept. of ECE, Malla Reddy College of Engineering

⁴ Assistant Professor, Dept. of ECE, Malla Reddy College of Engineering

⁵ Assistant Professor, Dept. of ECE, Malla Reddy College of Engineering

Abstract— In this paper a NAND flash memory controller was designed. For the best use of NAND type flash memory we design a new Arithmetical and Logical Unit (ALU) for calculating increment, addition, subtraction, decrement operations etc. In this memory controller we design single memory cell, memory module, a decoder etc. These all are encapsulated inside a controller and this is on top most in hierarchy. NAND flash memory is a non volatile storage media used in today daily life electronic equipments. NAND flash memory is programmed on page by page basis. Typically programming time is very less few micro second per page. This NAND flash memory controller architecture can be used with a real secure digital card, multimedia card (SD/MMC), digital cameras etc. The NAND Flash memory controller can be an internal device, built into the application processor or host, or designs can incorporate an external, stand-alone chip. Experimental results show that the designed controller give good performance and full fill all the systems specifications. We have used FPGA chip for download our code.

Keywords-Flash memory; Non Volatile; Arithmetical and Logical Unit (ALU); Encapsulation; Field Programmable Gate Array (FPGA); Secure Digital card/Multi Media Card (SD/MMC); Hard Disk Drive (HDD);

I. INTRODUCTION

Flash memory is being widely used as a storage medium in mobile devices because of its low power consumption, small form factor, and high resistance to shock and vibration. As the density of a flash memory chip increases and the price continues to drop, the flash memory is being adopted in more diverse storage applications. Flash memory is the combination of two technologies-EPROM and EEPROM. The term “Flash” means - A large chunk of memory (memory cell) could be erased at one time”. On the other hand in EEPROM each byte is erased one by one manner.

Flash memory has characteristics that are different from conventional storage devices such as HDD. Thus, specialized hardware and software are required to use flash memory as a storage device. The role of flash memory software is particularly important because it has to deal with the peculiarities of flash memory. It also needs to be diverse because flash memory is used in a wide spectrum of applications ranging from micro-embedded systems (e.g., a sensor-node) to large-scale servers [5]. Flash memory controller offers higher capacity for fast data transfer and random access of memory in I/O operations [1]. It is possible to design a simple memory mapped interface to hardware with NAND flash memory. NAND flash memory controller has also a bidirectional bus in between peripheral devices and controller,

controller internal bus for various functional blocks and controller with memory connections. For the improvement of product lifetime and system performance we always design an excellent NAND flash memory controller. Single Level Cell (SLC) and Multi Level Cell (MLC) two techniques are used for storing data in memory cells. SLC offers 100,000 erase program cycle while MLC offers about 10,000 erase program cycle[2].

NAND flash memory controller has also a bidirectional bus (Data, Address, and Control). NAND flash cells are placed together for saving 60% cell size over NOR flash cells. NAND flash memory controller provides a serial access of data blocks in a very high speed [6]. Single Level Cell (SLC) and Multi Level Cell (MLC) two techniques have been used for storing data in memory cells. A software called Flash Transaction layer (FTL) use for wear leveling and bad block management technique. All vendors provide FTL software[9].

The pipelining and parallel processing concepts are applied for systematic design approach of a systolic array processor. The systolic array architecture and iterative Very Large Scale Integration (VLSI) architecture is applied for good performance. It makes the circuit design easy for implementation[8].

II. NAND FLASH MEMORY CONTROLLER ARCHITECTURE

The capacity of NAND flash device is improved day by day, architecture are also improved day by day. Latest overall structure of NAND flash device is looks very similar to its conventional structure. A NAND flash controller implements memory mapped interface [10]. A multiplane array packs contains its own set of Cache/Data registers, more memory cells on a die and partitioned it into several plans. In multiplane array packs all operations performs parallels. Inside a single flash array operation time multiple pages of data can be programmed, read, write, fetched etc. so average data access time is small. In multiplane commands some addresses are restricted.

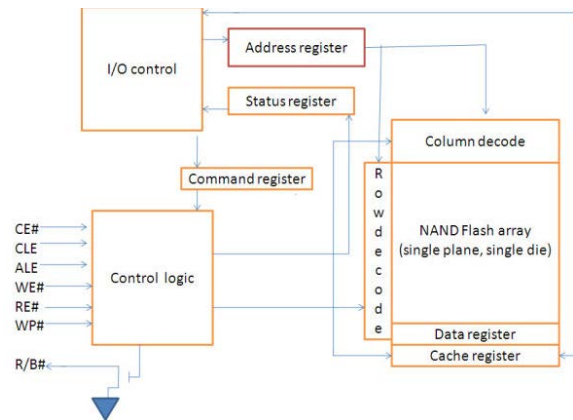


Figure 1. Block Diagram of a NAND Flash Memory Controller

NAND flash controller has flash chips. In today's life it is widely used in storage devices. One more recent application for flash memory is as a replacement for hard disks. Flash memory does not have the mechanical limitations and latencies of hard drives, so a Solid State Drive (SSD) is attractive when considering speed, noise, power consumption, and reliability. It always follows

Open NAND Flash Interface (ONFI) standard [3].

In NAND flash device we have mainly I/O control block, control logic, NAND flash array. A NAND flash array includes two dimensional NAND flash cells, Row/Column address decoder and cache / data registers [11]. It has a shared, multiplexed, bidirectional (command, address and data) I/O bus. Figure-1 shows the block diagram of a NAND Flash Memory Controller. A multiplane array packs contains its own set of Cache/Data registers, more memory cells on a die partitioned into several plane. In multiplane array packs, all operations are performed in parallel. Thus, inside a single flash array, multiple pages of data can be programmed, read,

write, fetched, so average data access time is reduced. In

multiplane commands some addresses are restricted. So new NAND flash chip with multi-die and multiplane support is always

increase performance, reduce the data access average time, and increase parallel execution of commands

[7]. NAND flash devices are programmed on a page by page basis. Typically programming time is a few hundred micro second per page. NAND flash cell can be programmed and erased only for limited time period (100,000 times for SLC and 10,000 times for MLC) before it fails. To improve this limitation, flash memory performance has been increased by using wear leveling technique. The technique spreads the memory cell use evenly to different physical pages. So the entire flash device is used equally to improve the life of flash memory [2]. Bad block management technique and wear leveling technique use some remapping technique of logical to physical address of the memory device. They all provide an FPGA to facilitate the implementation of a wider range of NAND Flash Memory Controller [4].

III. SIMULATION AND RESULT

A. Single Micro cell Module

In the simulation result, the NAND flash memory cell is simulated using Xilinx ISE Software and modelsim simulator. As shown in Figure 2, the RTL view of NAND Flash memory cell has been generated after the synthesis.

The modelsim waveform is displayed on Figure 3 indicating the write and read operation. Write operation takes place only when both word line and write enable are '1'. The q and qbar line are modified when this situation occurs as seen in the waveform and Read operation takes place when both word line and read enable should be high so that read out shows the data stored in q.

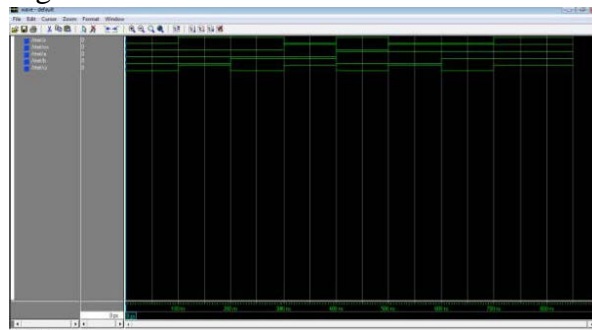
2. RTL Schematic View of Single Micro Cell
Figure 3. Simulation Waveform of Single Micro Cell

B. Full Adder

The simulation of full adder carried using Xilinx ISE Software and modelsim is shown in Figure 4. The RTL view of full adder was generated after the synthesis and it displays the

internal architecture of full adder. The modelsim waveforms are displayed in Figure 5 and depict the sum and carry output. Sum takes place only when any one input is high and carry operation is done when at least two inputs are high.

Figure



4. RTL Schematic

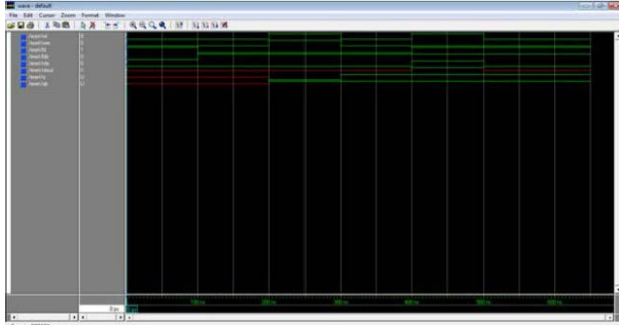
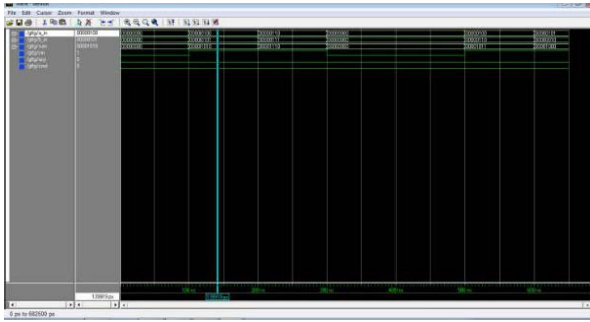


Figure 5. Simulation Waveform of Full Adder
Automatic View of Full Adder

C. Arithmetic and Logical Unit (ALU)

In the simulation, results of Arithmetic and Logical Unit (ALU) have been used in Xilinx ISE Software and modelsim simulator as shown in Figure 6. The RTL view of ALU has been generated after the synthesis and it displays the internal architecture of ALU. The modelsim waveform is displayed in Figure 7 which indicates all mathematical operations. The addition operation takes place only when op_sel. Operation select lines are zero and provide input value to the dat_a and dat_b and check the results on dat_out as well as all flag register like carry flag, Sign flag, auxiliary carry flag, parity flag, etc. Thus all mathematical operation can be carried by changing the value of op_sel.



D. Memory Module

In the simulation, result of Memory Unit using Xilinx ISE Software and modelsim simulator are shown in Figure

8. The RTL view of memory unit is generated after the synthesis to display the internal architecture of Memory Unit. The modelsim waveform is displayed in Figure 9. It indicates how the data can store in to the memory with the help of read and writeoperation.

E. Memory ReadCycle

In Figure 10, the RTL view of Memory Read Cycle has been generated after the synthesis to display the internal architecture of Memory Read Cycle. The modelsim waveform is displayed in Figure 11. During Memory Read Cycle when reset = '1' then both the mode operationare

zero and when apply the clock pulse the data at 1/4 and 3/4 points in data cell is generated and when increment the clock the data are in a position to go from serial to parallel conversion. After some time it will also shift to data register. In this way, data are shifted to the particular data register and finally read the data at that location.

F. Memory WriteCycle

In Figure 12, the RTL view of Memory Write Cycle has been generated after the synthesis to display the internal architecture of Memory Write Cycle. The modelsim waveform is displayed in Figure 13. During Memory Write Cycle when reset = '1' then

both the wrn1 and wrn2 operation is one and when enable the clock detect the edge on write pulse. After some time, detect edge on write pulse to load transmit buffer. When increment the clock the data are in a position to go from

transmit shift register to transmit buffer. In this way, data are shifted to the particular data register and finally write the data at that location.

G. NAND Flash Memory Controller

Figure 14 shows Xilinx RTL Schematic view of NAND Flash Memory Controller. Figure 15 are shows the Simulation Waveform of NAND Flash Memory Controller. We bind all the above components inside this module. This module is stand at the top of hierarchy. Various pins are described below:-

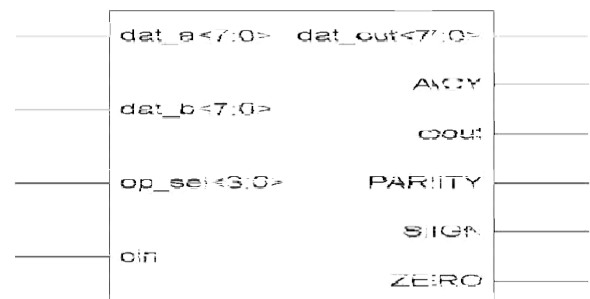
□ nand_ale : This

pin indicates NAND flash advanced latch enable when this pin is high, the NAND flash memory controller work and when it is low, the NAND flash memory controller are in latch mode.

□ nand_ce : This pin indicates NAND flash chip enable. When this pin is high the NAND flash memory controller are in working mode, it reflects that the data is storing in a memory in sequential order. When it is low, the NAND Flash memory controller do not worked.

□ nand_cle: This pin indicates NAND flash clear mode. When this pin is high the data are cleared in the main memory of NAND flash memory controller. When it is low it will not worked.

□ nand_re: This pin indicates NAND flash reset. When this pin is high the NAND flash memory controller are in reset mode i.e. all operations of NAND flash memory controller stopped. When it is low, it will work properly.



□ nand_tri_en: This pin indicates NAND flash tri- state enable. When it is high, it will indicate the data are in tri-state i.e. high impedance state. When it is low it may work properly.

□ nand_we : This pin indicates NAND flash

in write operation. When it is high, data are in writing process in a write mode i.e. we can write the data at particular memory address. When it is low, it will not provide a permission to write the data.

□ nand_opr<2:0> : This pin indicates selection between reset state (000), read IDstate (001),read page state (010) and write page state (011). After that state 100,101,110,111 (4 states) reserve for future extension.

□ nand_rdy : This is the NAND flash ready input signal from the memory device, only accessible when high. If it is low it will not be accessible.

□ prog_2,prog_3,...prog_24 :These 23 pins used for writestates

□ read_2,read_3,...read_21 : These 20 pins used for readstates.

□ rid_2, rid_3,,rid_9 : These 8 pins used for select IDstates.

□ rst_low:This pin indicates the reset input of the system. It is normally low.

□ rst_1, rst_2, rst_3 : These 3 pins used for reset states.

CONCLUSION

In this paper NAND flash memory controller for SD/MMC memory card using FPGA was designed. The test results show that NAND flash memory controller architecture will achieve a high performance. In the proposed NAND flash memory controller, all the blocks like microcell, microcontroller, ALU, fulladder,memoryunit,memoryreadcycle,memorywritecycle have beendevloped.Proposedarchitecturecanworkwithallthe embedded computing system as a replacement of conventional Hard Disk Drive (HDD) with a very huge size of NAND flash memory. In this controller we design only four states reset state, read ID state, read page state, write page state. In future extension we have four reservestates.

ACKNOW EDGMENT

This work was supported by ShriRam Collage of Engineering and Management, Banmore.

REFERENCES

[1]Shawn Kung, “Native PCIsSSD

ControllersNextGeneration Enterprise Architecture for Scalable I/O Performance”, White Paper Marvell Jan-2012.

[2] Yang Ou, Nong Xiao, “A ScalableMulti-channel

Parallel NAND Flash Memory Controller Architecture”, 6th Annual IEEE Chinagrid Conference, Page 48-53, 2011.

[3] Yu Cai, Haratsch, “FPGA Based Solid State Drive Prototyping Platform”, 19th IEEE AnnualInternational Symposium on Field-Programmable Custom Computing Machines (FCCM), Page 101-104, 2011.

[4] Yu Chi, Erich F. Haratsch, Mark McCatney andKen

Mai“FPGA-BasedSolid State Drive Prototyping Platform,” In IEEE International Symposium on Field Programmable Custom Computing Machines 2011.

[5] Yang Ou, Nong Xiao and Mingche Lai “A Scalable Multi-channel Parallel NAND Flash Memory Controller Architecture,” Sixth Annual ChinaGrid Conference2011.

[6] International Technology Roadmap for Semiconductor, 2007.

[7] Micron Technology, Boise, Idaho. Technical Note TN- 29-17 “Design and Use Considerations for NAND Flash Memory,” 2006.

[8] Altera Corporation, Stratix data isheet, May2003.

[9] Intel Corp., Understanding the Flash Transfer Layer (FTL) Specification,1998.

[10]Hoeseung Jung, Sanghyuk Jung, “Architecture ExplorationofFlashMemoryStorageControllerthroughAccurateProfiling”,IEEETransactionsonCustomerElectronics, Volume: 57, Page 1756–1764,2011.

[11]Teoh, J.N., Wong W.E., “FPGA Implementation of Nonlinear Control on Hard Disk Drive”, IEEE

Figure 15. Simulation Waveform of NAND Flash Memory Controller International Conference on Control and Automation, Page 609- 614, 2009.

